

Topics

- Robot Design, Development and Control
- Genetic Algorithms
- Fuzzy Control
- Machine Learning in Control Applications
- Distributed Control Systems
- Evolutionary Computation and Control
- Software Agents for Intelligent Control Systems
- Neural Networks based Control Systems
- Planning and Scheduling
- Intelligent Fault Detection and Diagnosis
- Humanoid Robots
- Cognitive Approach for Robotics
- Mobile Robots and Intelligent Autonomous Systems
- Control and Supervision Systems
- Telerobotics and Teleoperation
- Vehicle Control Applications
- Human-Robots Interfaces
- Network Robotics
- Autonomous Agents
- Intelligent Transportation Technologies and Systems
- Space and Underwater Robots
- Human-Machine Interfaces
- Collective and Social Robots
- Virtual Environment, Virtual and Augmented Reality
- Surveillance, Fault detection and Diagnosis

Keynote Speakers

Prof. Toshio Fukuda (IEEE, SICE, JSME, RSJ, and VRSJ Fellow)
Nagoya University, Japan
Prof. Yang Xiao (IET Fellow)
The University of Alabama, USA

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Publication

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Abstracting/Indexing: Index Copernicus, ProQuest, UDL, Google Scholar, Open J-Gate, **Scopus** (since 2016) etc.

Submission

- Please log in the **Electronic Submission System** to submit your full paper and abstract.
- Each paper should have no less than 4 pages normally, including all figures, tables, and references.

Venue

Nagoya Institute of Technology, Nagoya, Japan

